



# Digital Viticulture

Agrifutures - Viticulture Society of  
Canberra district

# Agrifutures opportunity:

## 1. UAV Mapping of vineyard block boundaries

“the entry point to precision viticulture”

## 2. Vineyard Sensing

- Top Down: Satellite, fixed wing, UAV
- Side on: “Greenseeker” NDVI & GoPro



# About the project...

- It's all about data collection!
- Representative, repeatable, traceable



# About me...

- Geologist:

- Sample Collection
- Database management
- Geographic Information Systems (GIS)

- Viticulturist – Penley Coonawarra

- Precision viticulture
- Field data specialist
- Wine Australia sponsored Nuffield Scholar:

“here come the robots, but what do we do with the data?”



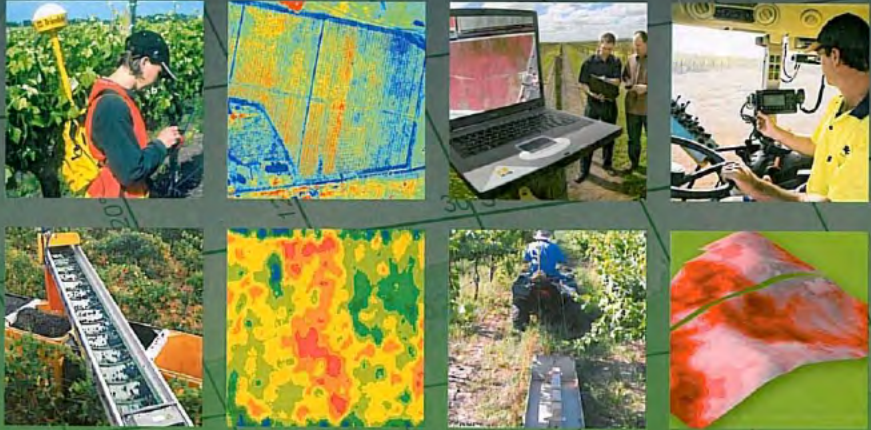
# Types of Sensing

Top down: RGB, PCD, NDVI, point cloud & photogrammetry/orthomosaic etc.



# Precision Viticulture

*A new era in vineyard management and wine production*



Tony Proffitt  
Rob Bramley  
David Lamb  
Erika Winter

“the entry point to precision viticulture”



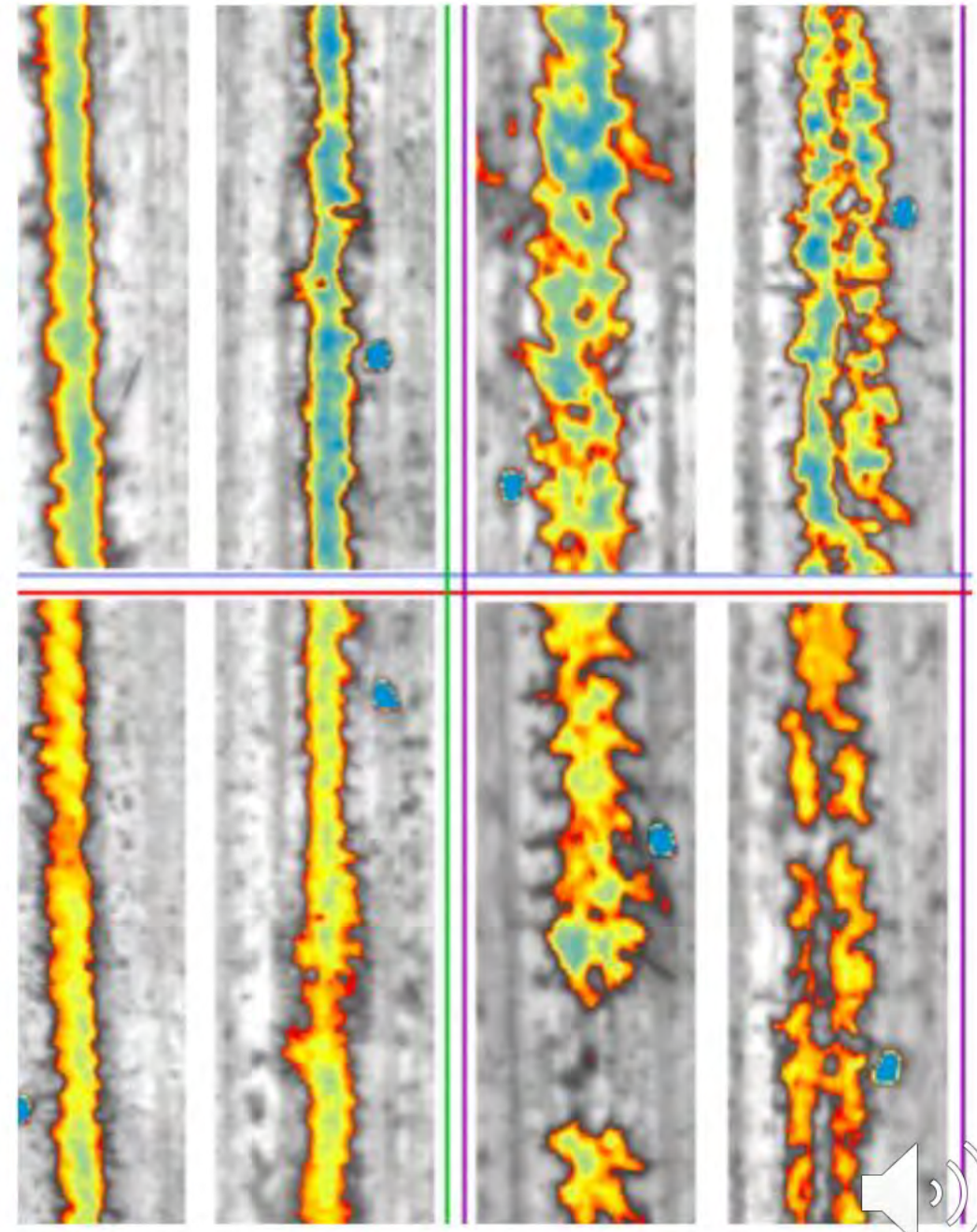
Coonawarra wine region  
Image © 2023 Airbus



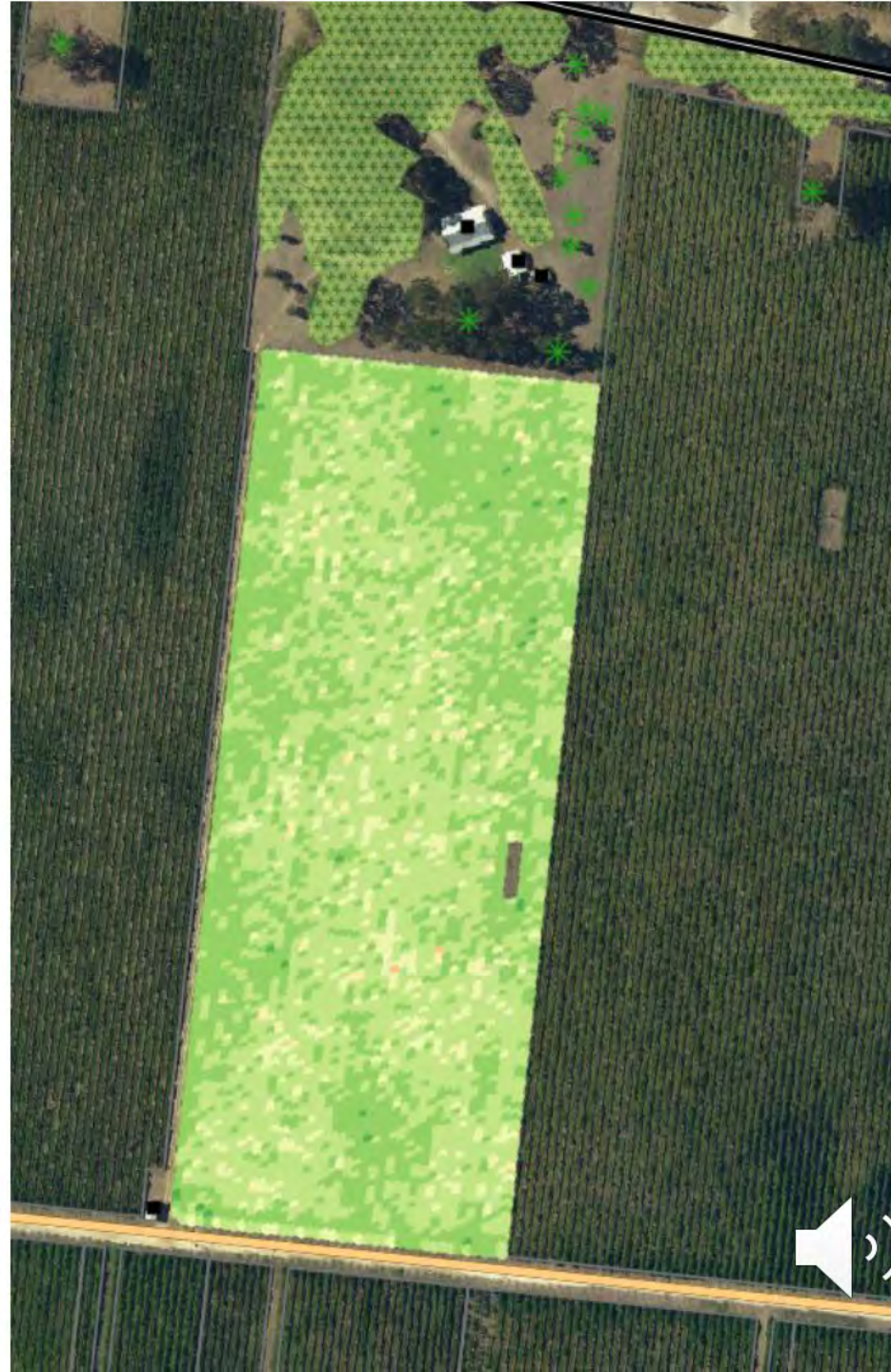
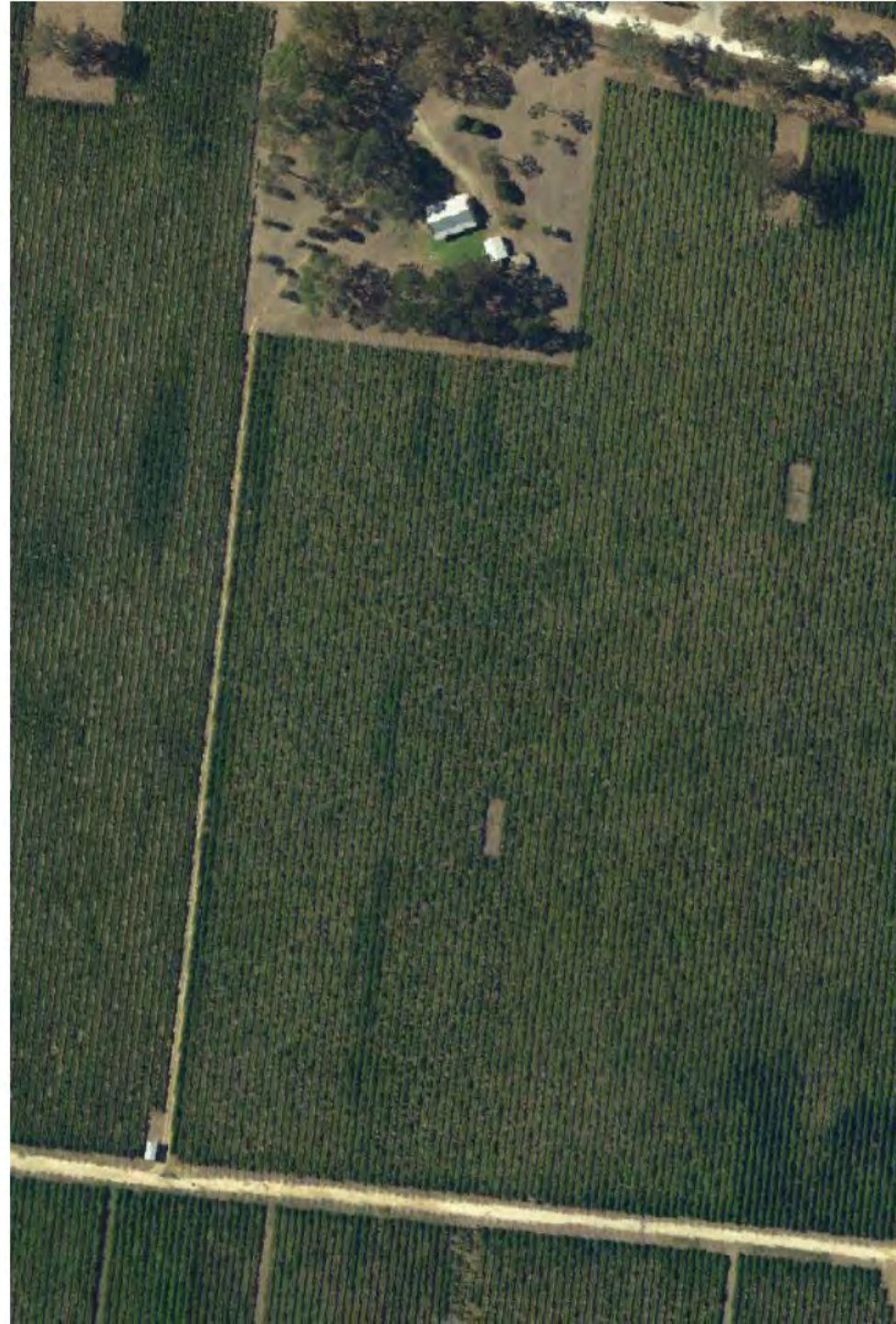
# Collection & Processing



Image: Grant Yates – Southern Precision



# RGB & NDVI





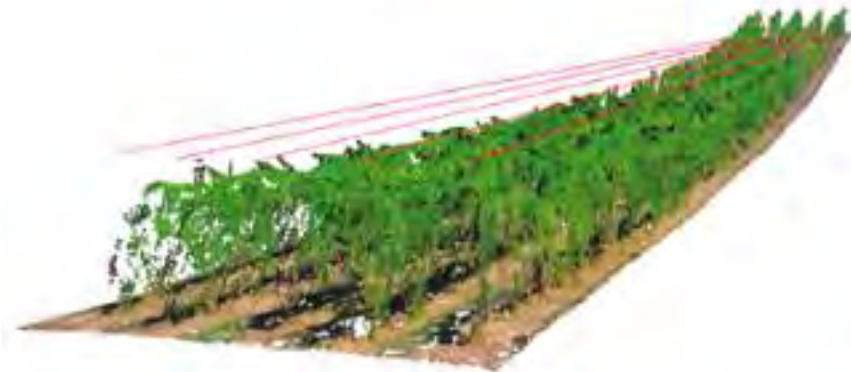
# Photogrammetry & Orthomosaics



[gis.stackexchange.com](https://gis.stackexchange.com)



# Photogrammetry & Orthomosaics



(a)



(b)

Example of a segmentation of vine rows: (a) visualisation of the 3D vine rows generated as presented in Pádua et al. [14]; and (b) 3D points selection in the point cloud, using a 60 cm buffer.

Source: Jurado, J.M., Padua, L., Feito, F.R., Sousa, J., 2020, Automatic Grapevine Trunk Detection on UAV-Based Point Cloud



# Types of Sensing

- Side on: RGB, NDVI, thermal, LiDar




















# Seasonal timing

- EL1 Dormancy
- EL4-9 First leaves
- EL12 Shoots 10cm
- EL Flowering
- EL33-38 Veraison



| Crop Type   | Phenological Stage | Net           | GoPro Setting   | Camera Angle  | Example   | Mounting  | GoPro View  |
|-------------|--------------------|---------------|---|---|---|---|---|
| Wine Grapes | EL1 - EL3          | nodes         | Video Resolution: <b>4K 4:3</b><br>Frames per second: <b>30</b><br>Field of View: <b>Linear + HL (Horizon Leveling)</b><br>HyperSmooth: <b>On</b> | <b>Camera Bottom and Facing Up</b><br>(35 to 45 degree)                                 |    |    |    |
|             | EL4 - EL12         | shoots        | Video Resolution: <b>4K 4:3</b><br>Frames per second: <b>30</b><br>Field of View: <b>Linear + HL (Horizon Leveling)</b><br>HyperSmooth: <b>On</b> | <b>Camera Bottom and Facing Up</b><br>(35 to 45 degree)                                 |    |    |    |
|             | EL12 - EL15        | inflorescence | Video Resolution: <b>4K 4:3</b><br>Frames per second: <b>30</b><br>Field of View: <b>Linear + HL (Horizon Leveling)</b><br>HyperSmooth: <b>On</b> | <b>Camera Side On</b><br>(Flowering Area in the Frame)                                  |    |    |    |
|             | EL15 - EL20        | canopy height | Video Resolution: <b>4K 4:3</b><br>Frames per second: <b>30</b><br>Field of View: <b>Portrait Mode</b><br>HyperSmooth: <b>On</b>                  | <b>Camera Side On</b><br>(Whole Post in the Frame -<br>Tips of the Shoots in the Frame) |   |   |   |
|             | EL32 - EL38        | bunches       | Video Resolution: <b>4K 4:3</b><br>Frames per second: <b>30</b><br>Field of View: <b>Linear + HL (Horizon Leveling)</b><br>HyperSmooth: <b>On</b> | <b>Camera Side On</b><br>(Fruiting Area in the Frame)                                   |  |  |  |



# Practical Considerations...



Image by pch.vector on Freepik

